


<b>Name:</b>	 <b>UPES</b> UNIVERSITY WITH A PURPOSE
<b>Enrolment No:</b>	
<b>UPES SAP ID:</b>	

**UNIVERSITY OF PETROLEUM AND ENERGY STUDIES**

**End Semester Examination, May, 2021**

**Course: Advanced Theory of Machines**

**Program: B.Tech – Mechanical**

**Course Code: MECH4024P**

**No. of Pages: 02**

**Semester: V**

**Time: 3 hours**

**Max. Marks: 100**

**Note:**

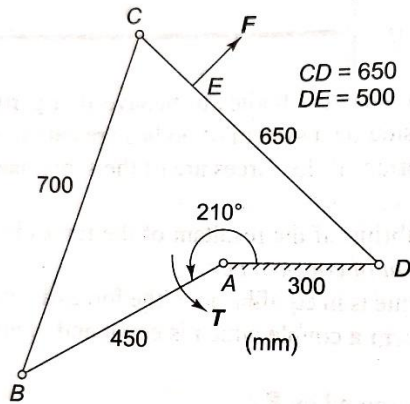
1. The paper consists of 3 sections A, B and C.
2. For Section A, type your answers in the browser directly
3. For Sections B and C, scan and upload your answers.
4. In Section C, Q12 has internal choice.

**Section A**

Q1.	Define centre of a body. Mention its types.	<b>5</b>	<b>CO1</b>
Q2.	Define following terms: a. Kinematic Mechanism b. Kinematic chain c. Degree of freedom d. Lower pair e. Higher pair	<b>5</b>	<b>CO1</b>
Q3.	Explain the terms sensitiveness and hunting of a governor.	<b>5</b>	<b>CO1</b>
Q4.	Define the terms coefficient of fluctuation of energy and coefficient of fluctuation of speed as applied to flywheel.	<b>5</b>	<b>CO1</b>
Q5.	Explain Bobillier theorem as applied to acceleration analysis.	<b>5</b>	<b>CO1</b>
Q6.	Explain the principle of virtual work.	<b>5</b>	<b>CO1</b>

**Section B**

Q7.	Each arm of a Porter governor is 250 mm long and is pivoted on the axis of rotation. The mass of each ball is 5 kg and the sleeve is 25 kg. The sleeve begins to rise when the radius of rotation of the balls is 150 mm and reaches the top when it is 200 mm. If the friction at sleeve is equivalent to 10 N, determine the range of speed, lift of sleeve, governor effort and power.	<b>10</b>	<b>CO3</b>
Q8	Design a four-link mechanism to coordinate three positions of the input and the output links given by $\theta_1 = 25^\circ \phi_1 = 30^\circ$ $\theta_2 = 35^\circ \phi_2 = 40^\circ$ $\theta_3 = 50^\circ \phi_3 = 60^\circ$	<b>10</b>	<b>CO2</b>
Q9	Determine the torque required to be applied to the link AB of the linkage shown in figure below to maintain the static equilibrium if $F = 100$ N. The lengths of the links are mentioned beside each link in mm.	<b>10</b>	<b>CO3</b>



Q10 A machine is coupled to a two-stroke engine which produces a torque of  $(800 + 180 \sin 3\theta)$  N.m, where  $\theta$  is the crank angle. The mean engine speed is 400 rpm. The flywheel and the other rotating parts attached to the engine have a mass of 350 kg at a radius of gyration of 220 mm. Calculate the

- Power of the engine
- Total percentage fluctuation of speed of the flywheel.

10 CO3

Q11 Derive the expressions for velocity and acceleration of a piston

10 CO3

**Section C**

Q12 While balancing a turbine rotor by the field balancing, the results obtained are shown in table below. Determine the correct balance masses to be placed in planes A and B at the same radii as for the trial masses. Also, determine the angular positions of the balance masses with respect to the trial masses to have the complete dynamic balance of the rotor.

20 CO4

No.	Trial mass (kg)	Plane A		Plane B	
		Amplitude (mm)	Phase angle (degrees)	Amplitude (mm)	Phase angle (degrees)
1.	0	$3 \times 10^{-3}$	25	$5 \times 10^{-3}$	70
2.	3 (in plane A)	$4.5 \times 10^{-3}$	110	$3.8 \times 10^{-3}$	135
3.	3 (in plane B)	$4 \times 10^{-3}$	60	$3.2 \times 10^{-3}$	215

**OR**

The following data relate to a four-link mechanism:

$$\begin{array}{llll}
 a = 55 \text{ mm} & m_a = 0.045 \text{ kg} & r_a = 28 \text{ mm} & \varphi_a = 0^\circ \\
 b = 165 \text{ mm} & m_b = 0.13 \text{ kg} & r_b = 85 \text{ mm} & \varphi_b = 15^\circ \\
 c = 80 \text{ mm} & m_c = 0.05 \text{ kg} & r_c = 42 \text{ mm} & \varphi_c = 0^\circ \\
 d = 150 \text{ mm} & & & 
 \end{array}$$

Complete force balancing by adding counterweights to the input and the output links is desired. Determine the mass-distance values and angular position of each counterweight.