

Name:			
Enrolment No:			
<b>UPES</b> <b>End Semester Examination, May 2024</b>			
<b>Course: Electrical Drives</b> <b>Program: B. Tech (Electrical Engineering)</b> <b>Course Code: EPEG 3026</b>		<b>Semester: VI</b> <b>Time : 03 hrs.</b> <b>Max. Marks: 100</b>	
<b>Instructions: Read all the questions carefully. Assume if any data is missing.</b>			
<b>SECTION A</b> <b>(5Qx4M=20Marks)</b>			
S. No.		Marks	CO
Q 1	Explain the principle of phase control. What is its significance?	4	CO1
Q 2	Describe various components of load torque? Explain briefly.	4	CO1
Q 3	List the factors affecting the selection of electric drives.	4	CO1
Q 4	With schematic explain single phase half bridge inverter.	4	CO2
Q 5	Classify different methods for slip power recovery? Explain Kramer drive briefly with neat sketch.	4	CO2
<b>SECTION B</b> <b>(4Qx10M= 40 Marks)</b>			
Q 6	Explain V/F method for controlling speed of induction motor.	10	CO3
Q 7	Describe various methods of speed control for DC motors. Explain with the help of equations in detail.	10	CO3
Q 8	With the help of neat sketch, waveform, and expression, explain the working of a single-phase full converter drive feeding a separately excited dc motor.	10	CO3
Q 9	A 4 pole, 50 Hz, 3 phase induction motor has rotor resistance of 0.2 $\Omega$ per phase and rotor standstill reactance of 1 $\Omega$ per phase. On full load it is running with a slip of 4 %. Calculate the extra resistance required in the rotor circuit per phase to reduce the speed to 1260 RPM, on the same load condition.	10	CO4
<b>SECTION-C</b> <b>(2Qx20M=40 Marks)</b>			
Q 10	The speed of a 10 HP, 210 V, 1000 rpm separately excited DC motor is controlled by a single-phase full converter. The rated motor armature current is 30 A, and the armature resistance is $R_a = 0.25 \Omega$ . The AC supply voltage is 230 V at 50 Hz. The motor voltage constant is $K_a\Phi = 0.172 \text{ V/rpm}$ . Assume that sufficient inductance is present in the armature	20	CO4

	<p>circuit to make the motor current continuous and ripple free. For a firing angle <math>\alpha = 45^\circ</math>, and rated motor armature current, determine: 1) The motor torque 2) Speed of the motor at rated armature current.</p>		
Q 11	<p>Describe torque slip characteristics of the induction motor and explain various regions for low, moderate, and high slip with the help of mathematical expressions.</p> <p style="text-align: center;">OR</p> <p>For a 3-phase delta connected 6-pole 50 Hz 400 V, 925 rpm squirrel cage induction motor is having <math>R_1 = 0.2 \Omega</math>, <math>R_2 = 0.3 \Omega</math>, <math>X_1 = 0.5 \Omega</math> and <math>X_2 = 1.1 \Omega</math>. The motor is operated from voltage source inverter with constant V/f ratio from 0 to 50 Hz and having a constant voltage of 400 V above 50 Hz frequency. Calculate: i). speed for a frequency of 35 Hz with half full load torque. (i) ii). Torque for a frequency of 35 Hz for a speed of 650 rpm.</p>	<b>20</b>	<b>CO4</b>